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Application No.10/535,125 Amendment dated August 11, 2010 Reply to Office Action of May 11, 2010 Attorney Docket No. 18062

AMENDMENTS TO THE CLAIMS

This listing of claims will replace all prior versions, and listings, of claims in the application:

1. (currently amended) A hydraulic steering device for centre pivot steered vehicles with a centre point steering joint between major ground-engaging components of the vehicles, comprising:

at least one hydraulic swiveling motor for producing the steering movement;

a hydraulic <u>variable flow</u> pump <u>with a variable flow rate-and</u> reversal of the direction of delivery, the <u>variable flow</u> pump in fluid flow communication with the at least one swiveling motor;

the at least one swiveling motor further being a swiveling vane motor that is in the form of a centre pivot steering joint of the centre point-steered vehicle or is arranged in the rotary axis of the centre point steering joint of the vehicle, the at least one swiveling motor having at least one first vane fixed in relation to the first ground-engaging component, and at least one moveable vane fixed in relation to the second ground-engaging component and wherein the at least one moveable vane pivots about the rotary axis with respect to the first ground engaging component;

wherein two connections of the variable flow pump are connected with two chambers of the swiveling vane motor in a first circuit such that a change at the

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adjusting actuator of the variable flow pump causes an inflow to one of the chambers and an outflow from the other chamber; and

hydraulic pump located in a second circuit configured to draw fluid from a reservoir for supplying the second circuit, wherein at least one valve permits the flow of fluid from the second circuit to supply the first circuit.

- 2. (previously presented) The steering device of claim 1, wherein: the variable flow pump with reversal of its delivery direction is also a constant displacement pump, and configured to be drivenly coupled to a controlled variable speed electric motor.
- 3. (previously presented) The steering device of claim 1, wherein: the variable flow pump with reversal of its delivery direction is a variable displacement axial piston pump with a swashplate, wherein the position of the swashplate with respect to pistons of the pump controls the direction and displacement of the pump.
- 4. (previously presented) The steering device of claim 1, wherein: at least one additional swiveling motor is arranged on an opposite side of the centre point steering joint from the at least one swiveling motor, wherein both motors are located along the rotary axis.
- 5. (previously presented) The steering device of claim 2, wherein: the at least one

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swiveling motor is arranged above and/or beneath the centre point steering joint along

the rotary axis.

6. (currently amended) The steering device of claim 1, wherein: the at least one

swiveling motor has at least a first and second chamber chambers are in fluid

connection with a first and second outlet of the pump and is arranged directly connected

to the chambers of the pump such that running the pump in a first direction delivers a

pressure to the first chamber steering the vehicle in a first direction and running the

pump in a second direction delivers a pressure to a second chamber for steering the

vehicle in a second direction.

7. (previously presented) The steering device of claim 1, further including: an electronic

controller connected to and controlling the direction and displacement of the pump.

8. (previously presented) The steering device of claim 7, wherein: the electronic

controller is configured to receive a steering signal from the operator, wherein the

controller is configured to convert the signal to a corresponding displacement volume

and either the first or second direction of flow of the pump, and transmit a signal to an

adjusting actuator connected to the swashplate, to change the swashplate to a position

corresponding to the determined displacement volume and direction.

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9. (previously presented) The steering device of claim 2, further including: sensors

configured to record steering angle and further system parameters of state are

positioned on the at least one motor.

10. (previously presented) The steering device of claim 3, further including: sensors

configured to record the steering angle and further system parameters of state are

positioned on the at least one motor.

11. (previously presented) The steering device of claim 7, further including: sensors for

recording the steering angle and further system parameters of state are positioned on

the at least one motor.

12. (previously presented) The steering device of claim 7, further including: a joystick

connected to said electronic control element for setting the steering angle of the vehicle.

13. (original) The steering device of claim 12, wherein the joystick includes a force-

feedback function.

14. (previously presented) The steering device of claim 11, further including: a joystick

connected to said electronic controller for setting the steering angle.

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15. (original) The steering device of claim 14, wherein the joystick includes a force-

feedback function.

16. (canceled)

17. (previously presented) The steering device of claim 11, further including: a set angle

prescribed by the operator is recorded in the micro-processor, and depending upon that

the quantity and direction of the volume flow to the at least one hydraulic steering motor

is influenced.

18. (original) The steering device of claim 17, wherein: the actual angle of the steering

device is recorded in the micro-processor and the volume flow to the steering motor is

controlled by a control algorithm which is selectively variable depending upon the

operating state of the vehicle, in particular a steering angle control and/or a steering

angle velocity controller.

19. (previously presented) The steering device of claim 1, wherein:

the swiveling motor is positioned inside of the joint such that a turning axle rigidly

connected to the first ground engaging component of a vehicle runs through the

swiveling motor that is rigidly mounted to a second part of the vehicle and bearing

points of the swiveling motor form a turning bearing between the first and the second

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ground engaging component of the vehicle.

20. (currently amended) The steering device of claim 1, A hydraulic steering device for centre pivot steered vehicles with a centre point steering joint between major ground-engaging components of the vehicles, comprising:

at least one hydraulic swiveling motor for producing the steering movement;

a hydraulic pump with a variable flow rate and reversal of the direction of delivery, the pump in fluid flow communication with the at least one swiveling motor;

the at least one swiveling motor further being a swiveling vane motor that is in the form of a centre pivot steering joint of the centre point-steered vehicle or is arranged in the rotary axis of the centre point steering joint of the vehicle, the at least one swiveling motor having at least one first vane fixed in relation to the first ground-engaging component, and at least one moveable vane fixed in relation to the second ground-engaging component and wherein the at least one moveable vane pivots about the rotary axis with respect to the first ground engaging component;

wherein two connection of the hydraulic pump with a variable flow rate are directly connected with two unions of the swiveling vane motor in a first circuit such that every change at an adjusting actuator of the pump causes an inflow to one of the unions and an outflow from the other union; and

the hydraulic pump with a variable flow rate and reversal of the direction of delivery mechanically by a driving mechanism that powers a second hydraulic pump

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located in a second circuit configured to draw fluid from a reservoir for supplying the second circuit, wherein at least one check valve permits the flow of fluid from the second circuit to the first circuit.